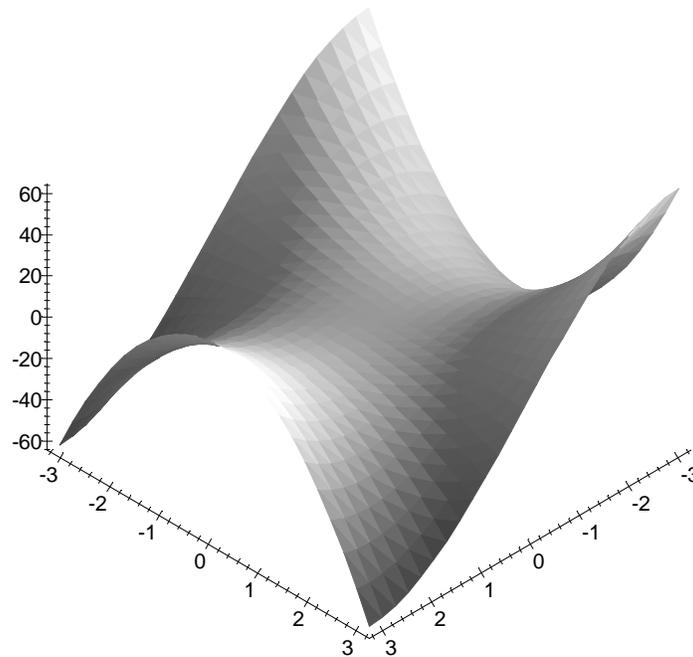


```
[ > restart:with(plots):
monkey.mws
The Monkey Saddle as a parametric Monge surface.
```

First, a picture:

```
[ > R:=[u,v,u^3-3*u*v^2];
>
R := [u, v, u^3 - 3 u v^2]
> plot3d(R(u,v),u=-Pi..Pi,v=-Pi..Pi,shading=zgayscale,lightmodel=light4,axes=framed,style=PATCHNOGRID);
```



Now restart the computation of the gauss and mean curvature using Cartan's Repere Mobile

```
[ > restart:with(linalg):
Warning, new definition for norm
Warning, new definition for trace
[ > with(diffforms):
> with(liessymm): setup(u,v):
Warning, new definition for `&^`
Warning, new definition for close
Warning, new definition for d
Warning, new definition for mixpar
Warning, new definition for wdegree
```

The Position Vector in R3 parametrized with (u,v). The example is for a Monge Surface $z=g(u,v)$

```
[ > RR:=[u,v,u^3-3*u*v^2];
RR := [u, v, u^3 - 3 u v^2]
[ > XX:=RR[1]:YY:=RR[2]:ZZ:=RR[3]:
[ > Yu:=diff(RR,u):
```

```
[ > Yv:=diff(RR,v):
[ > NNU:=crossprod(Yu,Yv):
[ Scale the adjoint normal field here by rho
[ > rho:=innerprod(NNU,NNU)^(1/2):
[ > #rho:=1:
[ >
[ This vector (surface normal) NNU can be computed from the Adjoint Matrix operation on the two
[ tangent vectors Yu and Yv. The basis frame utilizes this surface normal with arbitrary scaling
[ > NN:=( [factor(NNU[1]),factor(NNU[2]),simplify(factor(NNU[3])) ] ):
[ > FF:=array([ [Yu[1],Yv[1],NN[1]/rho],[Yu[2],Yv[2],NN[2]/rho],[Yu[3],Yv[3],NN[3]/rho]
[ o] ] );
```

$$FF := \begin{bmatrix} 1 & 0 & -3 \frac{(u-v)(u+v)}{\sqrt{9u^4 + 18u^2v^2 + 9v^4 + 1}} \\ 0 & 1 & 6 \frac{uv}{\sqrt{9u^4 + 18u^2v^2 + 9v^4 + 1}} \\ 3u^2 - 3v^2 & -6uv & \frac{1}{\sqrt{9u^4 + 18u^2v^2 + 9v^4 + 1}} \end{bmatrix}$$

```
[ The Repere Mobile or FRAME MATRIX, FF. note that the frame matrix is not orthonormal!!
[ > detFF:=simplify((det(FF)));
```

$$\det FF := \sqrt{9u^4 + 18u^2v^2 + 9v^4 + 1}$$

```
[ For the Monge casel the deteminant is non-zero globally, hence an inverse always exists.
```

```
[ > FFINVD:=evalm(FF^(-1)):
```

```
[ The 1-form components of the differential position vector with respect to the Basis Frame, F.
```

```
[ > dR:=innerprod(FFINVD,[d(XX),d(YY),d(ZZ)]):
```

```
[ > sigma1:=(wcollect(dR[1])):
```

```
[ > sigma2:=(wcollect(dR[2])):
```

```
[ Note that sigma1 is du and sigma2 is dv for a parametric Monge surfaces!!
```

```
[ > omega:=(wcollect(dR[3])):
```

$$\omega := 0$$

```
[ Note that this term vanishes for a parametric Monge surface, hence parametric Monge surfaces exhibit
[ no TORSION!! of the Affine type ( that is there is no translational shear defects!)
```

```
[ >
```

```
[ >
```

```
[ Compute the Cartan Matrix of connection forms from C=[F(inverse)] times d[F]
```

```
[ > dFF:=array([ [d(FF[1,1]),d(FF[1,2]),d(FF[1,3])],[d(FF[2,1]),d(FF[2,2]),d(FF[2,3])
[ ],[d(FF[3,1]),d(FF[3,2]),d(FF[3,3])]]):
```

```
[ > cartan:=evalm(FFINVD*dFF):
```

```
[ The interior connection coefficients (can be Christoffel symbols on the parameter space
```

```
[ > Gamma11:=(wcollect(cartan[1,1])):
```

```
[ > Gamma12:=(wcollect(cartan[1,2])):
```

```
[ > Gamma21:=(wcollect(cartan[2,1])):
```

```
[ > Gamma22:=(wcollect(cartan[2,2])):
```

```
[ The second fundamental form or shape matrix comes from the third row of the Cartan matrix
```

```
[ > h1:=(wcollect(cartan[3,1])):
```

```
[ > gamma1:=(wcollect(cartan[1,3])):
```

```
[ > h2:=(wcollect(cartan[3,2])):
```

```
[ > gamma2:=(wcollect(cartan[2,3])):
```

The abnormality for the parametric surface will show up as a non-zero entry in the [3,3] slot of the Cartan Matrix. Always an exact differential for parametric and Monge surfaces. Therefore implicit Monge surfaces will admit disclination defects (Torsion of the second kind due to rotations)

```
> Omega:=(wcollect(factor(simpform(cartan[3,3])))):
```

Omega vanishes for a given normalization.

```
> wcollect(factor(simpform(d(Omega)))):
```

```
> FROBOMEGA:=simpform(Omega&^d(Omega)):
```

The coefficients of the shape matrix determined from the Cartan matrix.

```
> factor(simpform(Omega&^gamma1)):
```

```
> simplify(Omega&^gamma1):
```

The components of the disclination 2-form are given above. Note that they are proportional to the Square Root of the Gauss Curvature (for scaling = 1) and form the "Stream" vector relative to the gradient of the Monge function g -- a symplectic rotation

```
> shape11:=-factor(gamma1&^d(v)/d(u)&^d(v)):
```

```
> shape12:=-factor(gamma1&^d(u)/d(v)&^d(u)):
```

```
> shape21:=-factor(gamma2&^d(v)/d(u)&^d(v)):
```

```
> shape22:=-factor(gamma2&^d(u)/d(v)&^d(u)):
```

```
>
```

```
> SHAPE:=array([[shape11,shape12],[shape21,shape22]]):
```

```
> HH:=simplify(trace(SHAPE)/2):
```

```
> print(`Mean Curvature is `,HH);
```

$$\text{Mean Curvature is , } -27 \frac{u(-2u^2v^2 - 3v^4 + u^4)}{(9u^4 + 18u^2v^2 + 9v^4 + 1)^{3/2}}$$

```
> KK:=simplify(det(SHAPE)):
```

```
> print(`Gauss Curvature is `,KK);
```

$$\text{Gauss Curvature is , } -36 \frac{u^2 + v^2}{(9u^4 + 18u^2v^2 + 9v^4 + 1)^2}$$

```
>
```

Note that the scaling of the normal or adjoint vector is a common factor of the formulas for the mean curvature and the Gauss curvature. Note the appearance of the Hessian of the Monge function.

The induce metric appears below

```
> GUN:=innerprod(transpose(FF),FF);
```

$$GUN := \begin{bmatrix} 1 + 9u^4 - 18u^2v^2 + 9v^4 & -18(u^2 - v^2)uv & 0 \\ -18(u^2 - v^2)uv & 1 + 36u^2v^2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

```
>
```

```
>
```

```
>
```